1 Simulation

We carried out a small simulation study to assess the finite sample properties of the proposed estimator. We generated 10000 samples of 1000 subjects each, from the model

$$C_{1} \sim Bernoulli(0.5)$$

$$C_{2} \sim N(0,1)$$

$$A \sim Bernoulli\{\exp(-0.5 + C_{1} + C_{2})\}$$

$$M \sim N(-1 + \beta_{1}A + C_{1} + C_{2}, 1)$$

$$T \sim Weibull \left[3, 0.8 \exp\left\{-\frac{1}{3}(-3 + \gamma_{1}A + \gamma_{2}M + C_{1} + 0.1C_{2})\right\}\right]$$

with $\beta_1 = \gamma_1 = 1$ and $\gamma_2 = 0.1$. The top-left panel of Figure 1 shows the marginal survival function S(t) = p(T > t) for this model. For t < 0.3 the survival function is fairly close to 1, and then drops quite steeply to 0.7 at t = 1. The top-right panel of Figure 1 shows the true PE functions $PE_{1,0}^1(t)$ (solid line) and $PE_{1,0}^0(t)$ (dashed line). We observe that these are fairly constant up to t = 0.3. When using the true values of $(\beta_1, \gamma_1, \gamma_2)$ in (3), we obtain the approximations $PE_{1,0}^1(t) \approx 0.14$ and $PE_{1,0}^1(t) \approx 0.05$, which agree fairly well with the true values observed in the top-right panel of Figure 1, up to t = 0.3.

For each sample we fitted a linear regression model for M and a Cox PH model for T, as in assumptions 2 and 3, respectively, with $h(C) = \beta_2 C_1 + \beta_3 C_2$ and $s(C) = \gamma_3 C_1 + \gamma_4 C_2$. We then used the fitted models to estimate $\text{PE}_{1,0}^1(t)$ and $\text{PE}_{1,0}^0(t)$ as in expression (3), together with 95% Wald confidence intervals. The bottom-left panel in Figure 1 shows the mean (over the 10000 samples) bias of the estimates, and the bottom-right panel shows the empirical coverage probability of the confidence intervals, i.e. the probability that the confidence intervals cover the true values of $\text{PE}_{1,0}^1(t)$ and $\text{PE}_{1,0}^0(t)$. We observe that, up to t = 0.3, the estimates are virtually unbiased, and that the coverage probabilities are fairly close to 95%. When t increases beyond t = 0.3, the estimates become increasingly biased, and the coverage probability decreases below the nominal 95%.

2 Derivations

Define $\Lambda_0(t) = \int_0^t \lambda_0(u) du$. Under the assumptions outlined in the main text we have that

$$S_{aM_{a^*}}(t) = \int_{m,c} \exp\left\{-\int_0^t \lambda(u|a,m,c)du\right\} p(m|a^*,c)p(c)dmdc$$

$$\approx 1 - \int_{m,c} \int_0^t \lambda(u|a,m,c)dup(m|a^*,c)p(c)dmdc$$

$$= 1 - \Lambda_0(t)\exp(\gamma_1 a) \int_c \exp\{s(c)\} \int_m \exp(\gamma_2 m)p(m|a^*,c)dmp(c)dc$$

$$= 1 - \Lambda_0(t)\exp(\gamma_1 a + \beta_1\gamma_2 a^* + \sigma^2\gamma_2^2/2) \int_c \exp\{s(c) + h(c)\gamma_2\}p(c)dc.$$

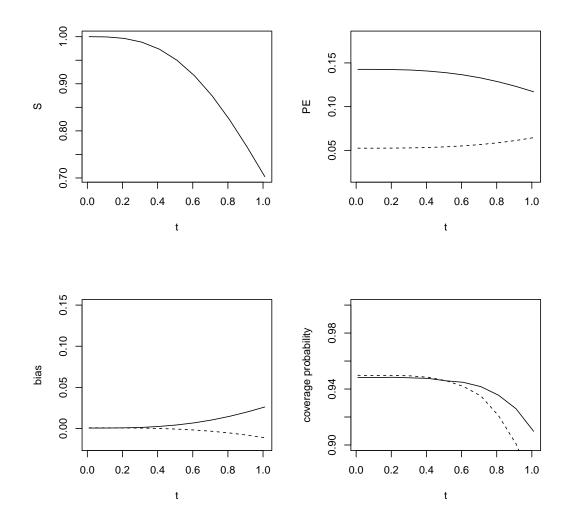


Figure 1: Simulation results. Top-left panel: marginal survival function; top-right panel: true PE functions $\text{PE}_{1,0}^1(t)$ (solid line) and $\text{PE}_{1,0}^0(t)$ (dashed line); bottom-left panel: mean bias of the estimated PEs; bottom-right panel: coverage probability of the 95% confidence intervals.

The first equality follows from assumption 1^1 , the approximation follows from assumption 4, the second equality follows from assumption 3, and the third equality follows from assumption 2, by utilizing the moment generating function $E\{\exp(Xk)\} = \exp(\mu k + \sigma^2 k^2/2)$ for the normal distribution. The expression in (3) now follows directly.

Let $\hat{\beta}_1$ be the maximum likelihood estimate of β_1 obtained from the fitted mediator model, and let $(\hat{\gamma}_1, \hat{\gamma}_2)$ be the partial likelihood estimate of (γ_1, γ_2) obtained from the fitted outcome model. Define $\theta = (\beta_1, \gamma_1, \gamma_2)^T$ and $\hat{\theta} = (\hat{\beta}_1, \hat{\gamma}_1, \hat{\gamma}_2)^T$. Finally, let $\psi_{a,a^*}^{a'}$ be the right-hand side of (3), and let $\hat{\psi}_{a,a^*}^{a'}$ be the right-hand side of (3) with θ replaced with $\hat{\theta}$. Using the delta method, together with standard results for (partial) maximum likelihood estimates, it follows that $\hat{\psi}_{a,a^*}^{a'}$ has an asymptotic normal distribution. The asymptotic variance of $\hat{\psi}_{a,a^*}^{a'}$ is given by

$$var(\hat{\psi}_{a,a^*}^{a'}) = \frac{d\psi_{a,a^*}^{a'}}{d\theta^T} var(\hat{\theta}) \frac{d\psi_{a,a^*}^{a'}}{d\theta}.$$
(1)

The asymptotic variance-covariance matrix $var(\hat{\theta})$ is obtained from the inverse Fisher information matricies of the fitted models; we note that $cov(\hat{\beta}_1, \hat{\gamma}_1) = cov(\hat{\beta}_1, \hat{\gamma}_2) = 0$ since β_1 and (γ_1, γ_2) are orthogonal. Finally, an estimate of $var(\hat{\psi}_{a,a^*}^{a'})$ is obtained by replacing θ with $\hat{\theta}$ in (1).

3 R code

The PE function below has six arguments. fitT is a fitted Cox PH model for the outcome, as obtained from the coxph function in the survival package. fitM is a fitted linear regression model for the mediator, as obtained from the lm function. A specifies the name of the exposure, as a string. a, astar and aprim specify the values of a, a^* and a' in (3). The function outputs a list with two elements; est (the estimate of $PE_{a,a^*}^{a'}(t)$) and var (the estimated variance).

```
library(numDeriv)
PE <- function(fitT, fitM, A, a, astar, aprim){
  if(aprim!=a & aprim!=astar)
    stop("aprim must be equal to a or astar")
  M <- as.character(fitM$call$formula[2])
  b1 <- fitM$coefficients[A]
  g1 <- fitT$coefficients[A]
  g2 <- fitT$coefficients[M]
  theta <- c(b1, g1, g2)
  tmp <- function(theta){
    b1 <- theta[1]
    g1 <- theta[2]
    g2 <- theta[3]
    return((exp(g1*aprim)*(exp(b1*g2*a)-exp(b1*g2*astar)))/</pre>
```

```
(exp((g1+b1*g2)*a)-exp((g1+b1*g2)*astar)))
}
est <- tmp(theta)
dPE <- matrix(grad(func=tmp, x=theta))
vb1 <- vcov(fitM)[A, A]
vg1 <- vcov(fitT)[A, A]
vg2 <- vcov(fitT)[M, M]
vg1g2 <- vcov(fitT)[A, M]
vcov <- matrix(c(vb1, 0, 0, 0, vg1, vg1g2, 0, vg1g2, vg2), 3, 3)
var <- as.vector(t(dPE)%*%vcov%*%dPE)
out <- list(est=est, var=var)
return(out)</pre>
```

References

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VanderWeele, T. Causal mediation analysis with survival data. *Epidemi-ology*. 2011;22:582–585.